U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE

ATTY. DOCKET NO. 170154.401C1 APPLICANTS Babak Habibi et al.

FILING DATE

August 6, 2003

APPLICATION NO. 10/634,874

INFORMATION DISCLOSURE STATEMENT

(Use several sheets if necessary)

U.S. PATENT DOCUMENTS

GROUP ART UNIT 3664

*EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIAT
	AA	4,011,437	03/08/77	Hohn	235	151.11	
	AB	4,187,454	02/05/80	Ito et al.	318	568	
	AC	4,294,544	10/13/81	Altschuler et al.	356	376	
	AD	4,523,809	06/18/85	Taboada et al.	350	163	
	AE	4,687,325	08/18/87	Corby, Jr.	356	1	
	AF	4,791,482	12/13/88	Barry et al.	358	107	
	AG	4,879,664	11/07/89	Suyama et al.	364	518	
	AH	4,985,846	01/15/91	Fallon	364	513	
	ΑI	5,160,977	11/03/92	Utsumi	356	376	
	AJ	5,208,763	05/04/93	Hong et al.	364	551.02	
	AK	5,325,468	06/28/94	Terasaki et al.	395	97	
	AL	5,446,835	08/29/95	Iida et al.	395	133	
	AM	5,461,478	10/24/95	Sakakibara et al.	356	375	
	AN	5,499,306	03/12/96	Sasaki et al.	382	291	
	AO	5,521,830	05/28/96	Saito	364	474.34	
	AP	5,568,593	10/22/96	Demarest et al.	395	82	
	AQ	5,608,818	03/04/97	Chini et al.	382	153	
	AR	5,715,166	02/03/98	Besl et al.	364	474.24	
	AS	5,745,523	04/28/98	Dent et al.	375	216	
	AT	5,784,282	07/21/98	Abitbol et al.	364	474.28	
	AU	5,802,201	09/01/98	Nayar et al.	382	153	
	AV	5,809,006	09/15/98	Davis et al.	369	275.4	
	AW	5,870,527	02/09/99	Fujikawa et al.	395	80	

* EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in

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*EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUBCLASS	FILING DATE IF APPROPRIATI
	AA	5,974,169	10/26/99	Bachelder	382	151	
	AB	6,004,016	12/21/99	Spector	364	167.02	
	AC	6,064,759	05/16/00	Buckley et al.	382	154	
	AD	6,278,906	08/21/01	Piepmeier et al.	700	250	
	AE	6,392,744	05/21/02	Holec	356	4.03	
	AF	6,463,358	10/08/02	Watanabe et al.	700	253	
	AG	6,490,369	12/03/02	Beiman	382	153	
	АН	6,516,092	02/04/03	Bachelder et al.	382	181	
	ΑI	6,529,627	03/04/03	Callari et al.	382	154	
	AJ	6,546,127	04/08/03	Seong et al.	382	152	
	AK	6,549,288	04/15/03	Migdal et al.	356	603	
	AL	6,580,971	06/17/03	Bunn et al.	700	259	
	AM	6,721,444	04/13/04	Gu et al.	382	154	
	AN	6,724,930	04/20/04	Kosaka et al.	382	154	
	AO	6,741,363	05/25/04	Kaupert	356	602	
	AP	6,748,104	06/08/04	Bachelder et al.	382	151	
	AQ	6,836,702	12/28/04	Brogårdh et al.	700	245	
	AR	6,970,802	11/29/05	Ban et al.	702	153	
	AS	7,006,236	02/28/06	Tomasi et al.	356	614	
	AT	7,009,717	03/07/06	Van Coppenolle et al.	356	603	
	AU	7,084,900	08/01/06	Watanabe et al.	348	94	
	AV	7,177,459	02/13/07	Watanabe et al.	382	151	

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Babak Habibi et al. FILING DATE GROUP ART UNIT August 6, 2003 3664

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	AA	2002/0019198	02/14/02	Kamono	451	41	
	AB	2002/0156541	10/24/02	Yutkowitz	700	28	
	AC	2003/0182013	09/25/03	Moreas et al.	700	145	
	AD	2004/0037689	02/26/04	Watanabe et al.	414	730	
	AE	2004/0041808	03/04/04	Ban et al.	345	419	
	AF	2004/0073336	04/15/04	Huang et al.	700	245	
	AG	2004/0081352	04/29/04	Ban et al.	382	154	
	AH	2004/0193321	09/30/04	Anfindsen et al.	700	257	
	AI	2005/0002555	01/06/05	Kumiya et al.	382	153	
	AJ	2005/0097021	05/05/05	Behr et al.	705	36	
	AK	2005/0126833	06/16/05	Takenaka et al.	180	8.1	
	AL	2005/0233816	10/20/05	Nishino et al.	473	131	
	AM	2005/0246053	11/03/05	Endou et al.	700	188	
	AN	2006/0025874	02/02/06	Huffington et al.	700	44	
	AO	2006/0088203	04/27/06	Boca et al.	382	153	
	AP	2006/0119835	06/08/06	Rastegar et al.	356	28	
	AQ	2006/0210112	09/21/06	Cohen et al.	382	103	
	AR	2007/0073439	03/29/07	Habibi et al.	700	213	
	AS	11/754,218		Habibi et al.			05/25/0
	AT	11/779,812		Habibi			07/18/0
	AU	11/833,187		Boca et al.			08/02/0
	AV	11/857,680		Boca et al.			09/19/0
	AW	60/719,765		Habibi et al.			09/23/0:

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	AA	60/808,903		Habibi et	al.				05/26	5/06
	AB	60/832,356		Habibi					07/20	0/06
	AC	60/845,932		Boca et al					09/19	9/06
	AD	60/875,073		Beis et al.					12/16	5/06
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		DOCUMENT NUMBER	DATE		COUNTRY				TRANS: YES	LATION NO
	AE	1 043 126	10/11/00	EP						
	AF	1 043 642	10/11/00	EP						
	AG	1 043 689	10/11/00	EP						
	AH	1 484 716	12/08/04	EP						
	ΑI	102 36 040	02/19/04	DE (+ abs	tract in English)					
	AJ	2000024973	01/25/00	JP (+ abst	ract in English)					
	AK	2005/074653	08/18/05	wo						
	AL	63288683	11/25/88	JP (+ abst	ract in English)					
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	OTHER PRIOR ART (Including	Author, Title, Date, Pertinent Pages, Etc.)				
AA	Aloimonos, J., et al., "Active Vision," IEEE, pp. 35-54, 1987.						
	Anonymous, "Precise Length Measu	urement at VSM (Vereinigte	Schmirgel-Und				
AB	Maschinen-Fabriken AG)," News of the Astech GMBH 2001(4), December 31, 2001.						
	Bajcsy, R., "Active Perception," <i>Proc. IEEE 76</i> (8):996-1005, 1988						
AC							
AD	Bakhtari, A., et al., "Active-Vision I	Based Multi-Sensor Surveill	ance – An Implementation,"				
	IEEE Transactions on Systems, Man	and Cybernetics, Part C: A	pplications and Reviews.				
	36(5):668-680, September 2006.		,				
	Borotschnig, H., et al., "Active Obje	ect Recognition in Parametri	c Eigenspace," Proc. 9th				
AE							
		British Machine Vision Conference, pp. 629-638, 1998.					
AF		Likelihood Framework for Determining Moving Edges," IEEE					
	Trans. Pattern Analysis and Machine Intelligence 11(5):499-511, 1989.						
AG	Brown, M., et al., "3D Model Acqui	, "3D Model Acquisition by Tracking 2D Wireframes," Proc. 11th British					
AG	Machine Vision Conference, pp. 656-665, 2000.						
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AH							
	International Conference on Pattern						
AI	Chaumette, F., "Potential Problems	ns of Stability and Convergence in Image-Based and					
'''	Position-Based Visual Servoing," in	g," in D. Kriegman, G. Hager and S. Morse, editors, The					
	Confluence of Vision and Control, V						
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	Sciences, pp. 66-78, Springer-Verlage						
AJ	Chaumette, F., et al., "Structure from	om Controlled Motion," IEEE Trans. Pattern Analysis					
	and Machine Intelligence 18(5):492	92-504, May 1996.					
	Constantinescu, D., et al., "Smooth a	and Time-Ontimal Trajector	v Planning for Industrial				
AK							
		ns," Journal of Robotic Systems 17(5):233-249, 2000.					
AL	Corke, P.I., et al., "A New Partitions						
	IEEE Trans. On Robotics and Auton	omation 17(4):507-515, August 2001.					
	Deguchi, K., "Optimal Motion Cont	rol for Image-Based Visual	Servoing by Decoupling				
AM			0.				
	Translation and Rotation," in Proc.	ini. Conj. intettigent kobots	ana systems, pp./05-/11,				
	October 1998.						
AN	Drummond, T., et al., "Real-time Tr	acking of Complex Structur	es with On-line Camera				
	Calibration," Proceedings of British	Machine Vision Conference	e, pp. 574-583, 1999.				
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		(Use several sheets if necessary)	FILING DATE	GROUP ART UNIT				
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	AA	Eriksen, R.D., et al., "Classification	onstrained 3D objects," 34th					
		International Symposium on Robotics, June 2-5, 2003, 7 pages.						
	AB	Hartley et al., Multiple View Geometry in Computer Vision, Cambridge University Pres. Cambridge, 2000						
	AC	Holliday et al., "Demonstration of A	"Demonstration of Automated Robotic Workcell for Hazardous Waste					
	AC	Characterization," Proceedings of the International Conference on Robotics and						
		Automation 3(10):788-794, May 2, 1993.						
		Hutchinson, S.A., et al., "Planning S		t Work Cell with Multi-				
	AD							
-		Sensor Capabilities," IEEE Trans. Robotics and Automation 5(6):765-783, 1989						
	AE	Hutchison et al., "A Tutorial on Visual Servo Control," IEEE Transactions on Robotics and						
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	AF	Lowe, D.G., "Robust Model-based Motion Tracking Through the Integration of Search and						
		Estimation," International Journal of Computer Vision 8(2):113-122, 1992.						
	AF	Macfarlane, S., et al., "Jerk-Bounded Manipulator Trajectory Planning: Design for Real-						
		Time Applications," IEEE Trans. Robotics and Automation 19(1):42-52, 2003.						
			ht Visually-Guided Pointing for a Humanoid Robot," XP-					
	AH	002220054, pp. 35-44, 1996.	, ,					
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	AI	Miura, J., et al., "Task-Oriented Generation of Visual Sensing Strategies in Assembly						
		Tasks," CMU School of Computer Science Tech Report CMU-CS-95-116, 42 pages, 1995.						
	AJ	Motai, Y., et al., "Concatenate Feature Extraction for Robust 3D Elliptic Object Localization," <i>Proc. Of the 19th ACM Symposium on Applied Computing</i> , pp. 21-28, 2004.						
	AK	Murase, H., et al., "Visual Learning		ects from Appearance,"				
		International Journal of Computer	r Vision 14(1):5-24, 1995.					
	AL	Naish, M.D., et al., "Coordinated dis	spatching of proximity sense	ors for the surveillance of				
		manoeuvring targets," Journal of Re-	botics and Computer Integr	ated Manufacturing				
		19(3):283-299, 2003.						
	AM	Nomura et al., "Integrated Visual Se	Nomura et al., "Integrated Visual Servoing System to Grasp Industrial Parts Moving on					
	AM	Conveyer by Controlling 6D0F Arm						
		International Conference 3:1768-17		, =				
		Papanikolopoulos et al., "Six Degree		ual Tracking with				
	AN	Uncertain Parameters," IEEE Transa						
		October 1995.	actions on nobolics and Am	o				
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		OTHER PRIOR ART (Including							
	AA	Sang, T., et al., "Vision Assisted Ro Mechatronics and Automation, pp.	of Sensor Planning in Computer Vision," IEEE						
	AB								
	AC	Tarabanis, K.A., et al., "The MVP S	tor Control Using Cartesian Position Based Visual						
	AD								
		<i>34</i> (2):487-498, 2001.							
	AE	Whaite, P., et al., "From Uncertainty Analysis and Machine Intelligence I							
	AF	Wilson et al., "Relative End-Effecto Servoing," <i>IEEE Transactions 12(5</i>)							
	AG		Zhou, F., et al., "Complete calibration of a structured light stripe vision sensor through planar target of unknown orientations," <i>Image and Vision Computing</i> 23:59-67, 2005.						
	АН	Office Action for U.S. Application l							
	AI	Amendment filed in U.S. Application	on No. 11/183,228, 24 pages	, Mail Date 04/05/2007.					
	AJ	Office Action for U.S. Application I	No. 11/183,228, 14 pages, N	1ail Date 06/08/2007.					
	AK	Amendment filed in U.S. Application	on No. 11/183,228, 8 pages,	Mail Date 09/04/2007.					
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